# FOXTAM ELECTRICAL MEASUREMENT TRANSDUCERS



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# **GENERAL SPECIFICATIONS & DIMENSIONS**

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Response time:	<400mSec
Warm up time:	<15 mins
Output ripple:	1% peak full scale
Long term drift:	+/- 0.25% per year non cumulative
Maximum load:	0-1mA 10 KOhm max
	0-2.5mA 6 KOhm max
	0-5mA 3 KOhm max
	0-10mA 1.5 KOhm max
	0-20mA
Adjustment:	Self powered voltage & current transducers have an adjustable span only
	All other transducers have an adjustable zero & span

### AUXILIARY SUPPLY

AC:	24 / 110 / 230 / 415V others on request
DC:	24 / 48 / 110V
Tolerance:	+/- 20%
Consumption:	4VA / W (combined Watt / VAr transducers 7VA / W)

## EMC COMPLIANCE

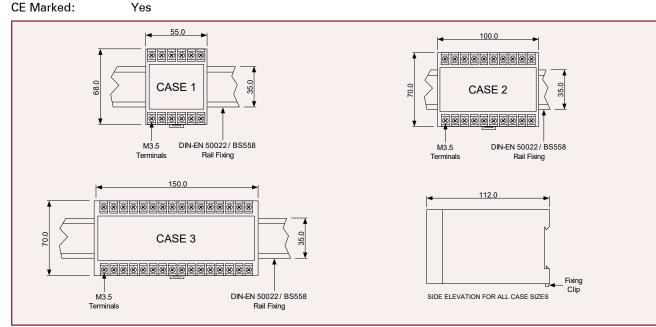
Directive 89/36/EEC: Electrostatic discharge IEC801.2 (8KV) Electromagnetic fields IEC801.3 level 3 Fast transient bursts IEC801.4 level 4 Surge withstand IEC255-5

### ENCLOSURE

Material: Isolation:

Mounting:

Grey ABS plastic with finger proof terminal covers 4KV rms 50Hz for 1 min (to IEC414) between input / output / case / auxiliary supply 1KV DC / 600VAC between outputs on combined Watt / VAr transducers 35mm Din rail (DIN-EN 50022) Yes



See individual transducer data sheets for unit specific specification details

# **DC CURRENT TRANSDUCERS**

TYPE: FOX.TR.DI



#### DESCRIPTION

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Foxtam DC current transducers can measure DC current directly up to 10 Amps, above 10 Amps a shunt should be used in conjunction with a DC voltage transducer type FOX.TR.DU. The transducer converts the input signal to either a DC mA or DC voltage analogue signal output, directly proportional to the input. All DC current transducer require an auxiliary supply voltage. The 4KV isolated output signals can be utilised for many applications and can be fed into analogue meters, digital meters, PLC's or BMS systems.

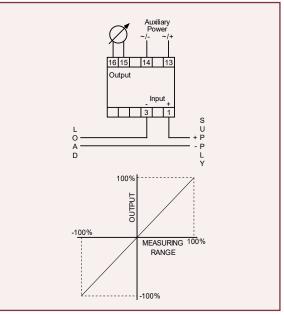
Transducer types include:-

FOX.TR.DI.U - Uni-polar output for example 4-20mA or 0-10VDC.

**FOX.TR.DI.B** – Bi-polar transducers which are particularly applicable for renewable energy applications when charging and discharging batteries. Also for applications involving the control of DC motors when reversing polarity to control direction of motion, outputs for example can be 4-12-20mA or -10VDC to 0 to +10VDC.

#### SPECIFIC SPECIFICATIONS

- Accuracy: Input current: Overload:
- Working range: Input Burden: Case size:
- Class 0.25 0-1mA...10A direct 2 x In continuous 30 x In for 1 sec 0-120% In <0.3VA 1



#### ORDERING INFORMATION

<u>TYPE</u>	INPUT RANGE	OUTPUT UNI	OUTPUT BI	AUX SUPPLY
FOX.TR.DI.U / Uni-polar	0-1mA10A direct*	0-1mA	+/-1mA	24VAC
FOX.TR.DI.B / Bi-polar		0-2.5mA	+/-2.5mA	63VAC
		0-5mA	+/-5mA	110VAC
		0-10mA	+/-10mA	230VAC
		0-20mA	+/-20mA	415VAC
		4-20mA	4-12-20mA**	24VDC
		0-1VDC	+/-1VDC	48VDC
		0-5VDC	+/-5VDC	110VDC
		0-10VDC	+/-10VDC	

\*Specify exact current input

\*\*Also possible on bi-polar units to have as an example 0-5-10VDC output